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IN AN APPLICATIONAPPLICANT: Robert K. Jenner, *et al.*

FILING DATE: 09/21/2000

GROUP: 2812

3726

## U.S. PATENT DOCUMENTS

EXAMINER INITIAL		DOCUMENT NUMBER	DATE	NAME	CLASS	SUB- CLASS	FILING DATE IF APPROPRIATE
<i>mg</i>	AA	5,388,119	02/07/1995	Cronin, <i>et al.</i>	372	69	
<i>1</i>	AB	5,745,624	04/28/1998	Chan, <i>et al.</i>	385	91	
<i>mg</i>	AC	6,103,988	08/15/2000	Kim	219	121.63	
	AD						
	AE						
	AF						
	AG						

## FOREIGN PATENT DOCUMENTS

		DOCUMENT NUMBER	DATE	COUNTRY	CLASS	SUB- CLASS	TRANSLATION YES NO
<i>mg</i>	AH	EP 0 030 617 A2 ✓	05 NOV 1980	EP	G02B	7/26	X
Concise Explanation: this reference shows a filter splicer							
<i>mg</i>	AI	WO 00/41021 ✓	13 JUL 2000	PCT	G02B	6/42	X
	AJ						
	AK						

## OTHER DOCUMENTS (Including Author, title, Date, Pertinent Pages, Etc.)

<i>mg</i>	AL	Goldfarb, Michael; Speich, John E., "Design of a Minimum Surface-Effect Three Degree-of-Freedom Micromanipulator," Proceedings of the 1997 IEEE International Conference on Robotics and Automation, Albuquerque, New Mexico - April 1997.
<i>mg</i>	AM	Goldfarb, Michael; Speich, John E., "Eliminating Non-Smooth Nonlinearities With Compliant Manipulator Design." Proceedings of the American Control Conference, Philadelphia, Pennsylvania - June 1998.
<i>mg</i>	AN	Heinen, Simon; Aymon, Cédric; Bottinelli, Stefano; Clavel, Reymond, "Articulated Structures With Flexible Joints Dedicated to High Precision." Département de Microtechnique, Institute de Systèmes Robotiques (DMT-ISR), Swiss Federal Institute of Technology Lausanne (EPFL), EPFL CH-1015, Lausanne, Switzerland.
<i>mg</i>	AO	Speich, John E.; and Goldfarb, Michael, "A Three Degree-of-Freedom Flexure-Based Manipulator for High Resolution Spatial Micromanipulation." Part of the SPIE Conference on Microrobotics and Micromanipulation, Boston, Massachusetts, November 1998. SPIE Vol. 3519.

EXAMINER

DATE CONSIDERED

*Marc J. Jenner**August 23, 2002*